

# Stability Analysis Methodology for Epidemiological Models

Paola Lizarralde-Bejarano

Supervisor: María Eugenia Puerta  
Co-supervisor: Sair Arboleda-Sánchez  
EAFIT University  
Medellín, Colombia

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1 Preliminar

2 Stability

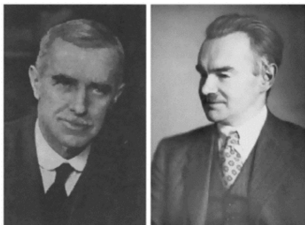
3 Bibliography



**Figure:** *Aedes aegypti*. Image taken from <https://goo.gl/tneEZY>

Determine the most relevant components of the mathematical models based on Ordinary Differential Equations (ODE) in order to understand the transmission of an infectious disease.

# Epidemiological models



**Figure:** McKendrick (1876 - 1943) and Kermack (1898 - 1970).

Image taken from <https://goo.gl/GN0cAF>

# Epidemiological models

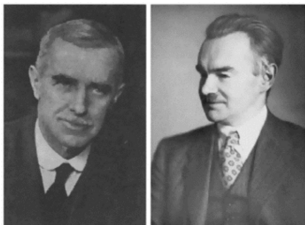


Figure: McKendrick (1876 - 1943) and Kermack (1898 - 1970).

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Figure: Flow chart for the SIR model<sup>3</sup>

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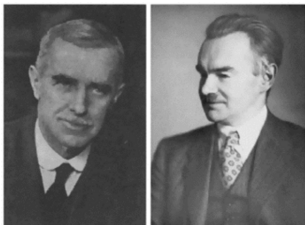


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Figure: Flow chart for the SIR model<sup>3</sup>

# Epidemiological models

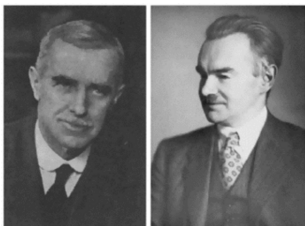


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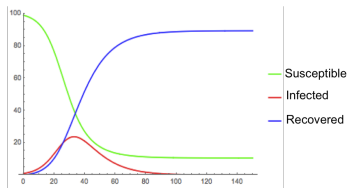


Figure: SIR Model

# Threshold theorem (basic reproductive number, $R_0$ )

$R_0$  for SIR model

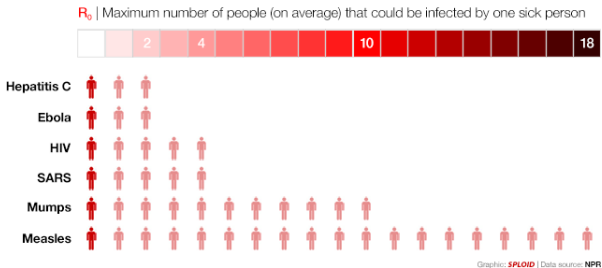
$$R_0 = \frac{\beta S_0}{\gamma}$$



# Threshold theorem (basic reproductive number, $R_0$ )

$R_0$  for SIR model

$$R_0 = \frac{\beta S_0}{\gamma}$$



**Figure:** Basic reproductive number for some infectious disease. Image taken from <https://goo.gl/vDc70u>

## Example: Dengue model, Bello's case

$$\frac{dA}{dt} = \delta \left( 1 - \frac{A}{C} \right) M - (\gamma_m + \mu_a) A$$

$$\frac{dM_s}{dt} = f \gamma_m A - b \beta_m \frac{H_i}{H} M_s - \mu_m M_s$$

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$$\frac{dH_r}{dt} = \gamma_h H_i - \mu_h H_r$$

## Example: Dengue model, Bello's case

$$\begin{aligned} R_0 &= \frac{b^2 \beta_m \beta_h \theta_h \theta_m}{(\theta_m + \mu_m)(\gamma_h + \mu_h)(\theta_h + \mu_h)\mu_m M} \cdot \frac{f \gamma_m}{\mu_m} \frac{\delta M C}{(\delta M + C(\gamma_m + \mu_a))} \\ &= \frac{b^2 \beta_m \beta_h \theta_h \theta_m}{(\theta_m + \mu_m)(\gamma_h + \mu_h)(\theta_h + \mu_h)\mu_m} \cdot \frac{M_s^*}{M} \end{aligned}$$

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The Basic Reproductive Number ( $R_0$ ) of the epidemic occurred in Bello in 2010 was between 1.5 and 2.7.

# Epidemiological data

The parameters used in the model, their biological descriptions, and their ranges of values.

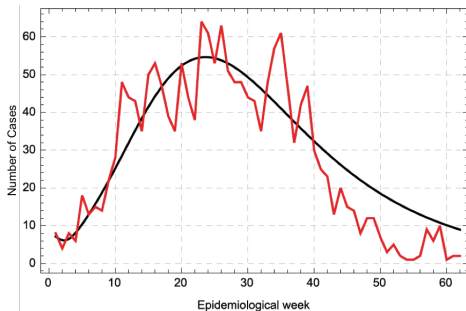
Param.	Meaning	V. / day	V. / week
$b$	Biting rate	[0, 1]	[0, 4]
$\delta$	Per capita oviposition rate	[8, 24]	[55, 165]
$\gamma_m$	Transition rate from the aquatic phase to the adult phase	[0.125, 0.2]	[0.875, 1.4]
$\mu_a$	Mortality rate in the aquatic phase	[0.001, 0.5]	[0.007, 0.3]
$\mu_m$	Mortality rate in the adult phase	[0.008, 0.03]	[0.06, 0.20]
$f$	Fraction of female mosquitoes hatched from all eggs	[0.42, 0.55]	[0.42, 0.55]
$C$	Carrying capacity of the environment	[6400, 95000]	[6400, 95000]
$\mu_h$	Birth and death rate of the human population	0.00006	0.0004
$\beta_h$	Transmission probability from mosquito to human	[0, 1]	[0, 1]
$\beta_m$	Transmission probability from mosquito to human	[0, 1]	[0, 1]
$\theta_m$	Transition rate from exposed to infectious mosquitoes	[0.08, 0.13]	[0.58, 0.88]
$\theta_h$	Transition rate from exposed to infectious humans	[0.1, 0.25]	[0.7, 1.75]
$\gamma_h$	Recovery rate	[0.07, 0.25]	[0.5, 1.75]

# Initial conditions

The initial conditions used in the model, their descriptions, and their ranges of values.

Initial condition	Meaning	Range
$A(0)$	Initial condition for the aquatic phase	[5755, 17265]
$M_s(0)$	Initial condition for susceptible mosquitoes	[0, 1200000]
$M_e(0)$	Initial condition for exposed mosquitoes	[0, 100]
$M_i(0)$	Initial condition for infectious mosquitoes	[0, 100]
$H_s(0)$	Initial condition for susceptible humans	[244402, 321734]
$H_e(0)$	Initial condition for exposed humans	[18, 72]
$H_i(0)$	Initial condition for infectious humans	[6, 24]
$H_r(0)$	Initial condition for recovered humans	[81405, 158809]

# The model fitted to the real biological data



— Estimated Cases 2009 - 2010  
— Epidemic 2009 - 2010

Param.	Value
$\delta$	65
$\gamma_m$	1.4
$\mu_a$	0.1156
$b$	4
$\mu_m$	0.12
$\theta_m$	0.58
$f$	0.5
$\theta_h$	0.7
$C$	10000
$\gamma_h$	1
$\beta_m$	0.6
$\beta_h$	0.15
$\mu_h$	0.0004
$A(0)$	9000
$M_s(0)$	1199976
$M_e(0)$	18
$M_i(0)$	6
$H_s(0)$	321710
$H_e(0)$	18
$H_i(0)$	6
$H_r(0)$	81501

# Stability analysis



**Figure:** Henri Poincaré (April 29, 1854 - July 17, 1912). Image taken from <https://goo.gl/0I0qLJ>



**Figure:** Aleksandr Lyapunov (June 6, 1857 - November 3, 1918). Image taken from <https://goo.gl/dLNfwW>



# Stability analysis



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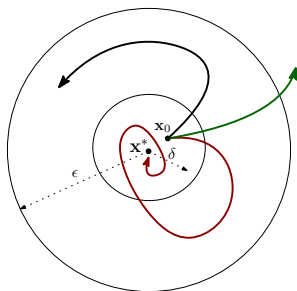


**Figure:** Aleksandr Lyapunov (June 6, 1857 - November 3, 1918). Image taken from <https://goo.gl/dLNfW>

## Definition

A point  $\mathbf{x}^*$  is called an *equilibrium point* of  $\dot{\mathbf{x}} = \mathbf{f}(\mathbf{x})$ , if  $\mathbf{f}(\mathbf{x}^*) = 0$ .

## Definitions: stable, unstable and asymptotically stable



**Figure:** The **black** line shows the definition of *stable* point. The **green** line shows the definition of *unstable* point. The **red** line represents a definition of *asymptotically stable* point.

# Definitions: stable, unstable and asymptotically stable

## Definition

The equilibrium point  $\mathbf{x}^*$  is

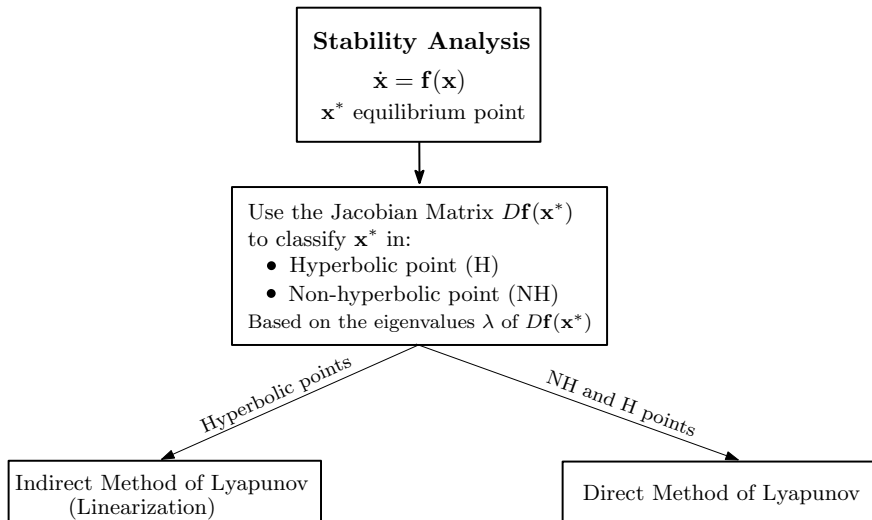
- *stable* if, for each  $\epsilon > 0$ , there is a  $\delta = \delta(\epsilon) > 0$  such that,

$$\|\mathbf{x}^0 - \mathbf{x}^*\| < \delta \Rightarrow \|\varphi(t, \mathbf{x}^0) - \mathbf{x}^*\| < \epsilon, \quad \forall t \geq 0$$

- *unstable*, if not stable
- *asymptotically stable*, if it is stable, and  $\delta$  can be chosen such that

$$\|\mathbf{x}^0 - \mathbf{x}^*\| < \delta \Rightarrow \lim_{t \rightarrow \infty} \|\varphi(t, \mathbf{x}^0) - \mathbf{x}^*\| = 0$$

# Stability diagram



The following results were taken from (Hale and Koçak, 2012).

## Theorem

*Let  $\mathbf{f}$  be a  $C^1$  function. If all eigenvalues of the Jacobian matrix  $D\mathbf{f}(\mathbf{x}^*)$  have negative real parts, then the equilibrium point  $\mathbf{x}^*$  of  $\dot{\mathbf{x}} = \mathbf{f}(\mathbf{x})$  is asymptotically stable.*

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## Theorem

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## Theorem

*Let  $\mathbf{f}$  be a  $C^1$  function. If at least one of the eigenvalues of the Jacobian matrix  $D\mathbf{f}(\mathbf{x}^*)$  has positive real part, then the equilibrium point  $\mathbf{x}^*$  of  $\dot{\mathbf{x}} = \mathbf{f}(\mathbf{x})$  is unstable.*

## Theorem

*(Grobman (1959) - Hartman(1960)) If  $\mathbf{x}^*$  is a hyperbolic equilibrium point of nonlinear system  $\dot{\mathbf{x}} = \mathbf{f}(\mathbf{x})$ , then there is a neighborhood of  $\mathbf{x}^*$  in which  $\mathbf{f}$  is topologically equivalent to the linear vector field  $\dot{\mathbf{x}} = D\mathbf{f}(\mathbf{x}^*)\mathbf{x}$ .*

# Direct method of Lyapunov

The following result was taken from (Khalil, 1996).

## Theorem

Let  $\mathbf{x}^* = \mathbf{0}$  be an equilibrium point of  $\dot{\mathbf{x}} = \mathbf{f}(\mathbf{x})$ . Let  $V : D \rightarrow \mathbb{R}$  be a continuously differentiable function on a neighborhood  $D$  of  $\mathbf{x}^* = \mathbf{0}$ , such that

$$V(\mathbf{0}) = 0 \text{ and } V(\mathbf{x}) > 0 \text{ in } D - \{\mathbf{0}\}$$

$$\dot{V}(\mathbf{x}) \leq 0 \text{ in } D$$

then,  $\mathbf{x}^* = \mathbf{0}$  is stable. Moreover, if

$$\dot{V}(\mathbf{x}) < 0 \text{ in } D - \{\mathbf{0}\}$$

then  $\mathbf{x}^* = \mathbf{0}$  is asymptotically stable.



# Exponentially stable

## Definition

The equilibrium point  $\mathbf{x}^* = 0$  of  $\dot{\mathbf{x}} = \mathbf{f}(\mathbf{x})$  is said to be exponentially stable if

$$\|\mathbf{x}(t)\| \leq k\|\mathbf{x}(0)\|e^{-\lambda t}, \quad \forall t \geq 0$$

$k \geq 1$ ,  $\lambda > 0$ , for all  $\|\mathbf{x}(0)\| < c$ .

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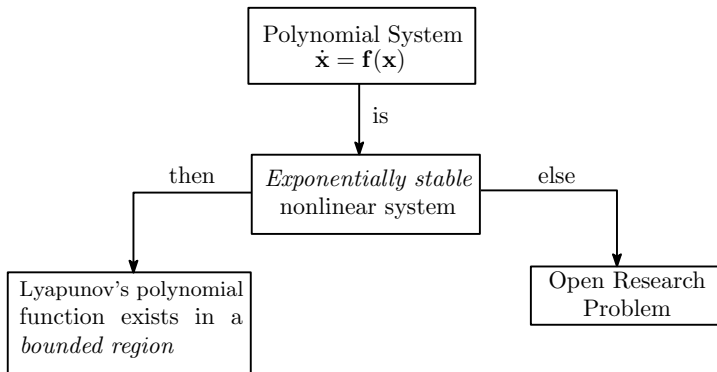
## Definition

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## Theorem

*The equilibrium point  $\mathbf{x}^* = 0$  of  $\dot{\mathbf{x}} = \mathbf{f}(\mathbf{x})$  is exponentially stable if and only if the linearization of  $\mathbf{f}(\mathbf{x})$  at the origin is a Hurwitz matrix.*

# How to find a Lyapunov function?



For a deeper discussion of when a Lyapunov's polynomial function exists in a bounded region we refer the reader to (Peet, 2009).

## Counterexample

The system (1) does not admit a polynomial Lyapunov function of any degree.

$$\begin{aligned}\dot{x} &= -x + xy \\ \dot{y} &= -y\end{aligned}\tag{1}$$

See (Ahmadi et al., 2011) for details of this result.

# How to find a Lyapunov function?

Definition of Lyapunov function

$$V(x) \geq 0$$

$$\dot{V} = \sum_{i=1}^n \frac{\partial V}{\partial x_i} \dot{x}_i = \left\langle \frac{\partial V}{\partial \mathbf{x}}, \dot{\mathbf{x}} \right\rangle$$

$$\dot{V} \leq 0$$

Relaxation of constraints

$V(x)$  is a Sum of Squares (SOS)

$-\dot{V}(x)$  is a Sum of Squares (SOS)

# Can we apply this results to epidemiological models?

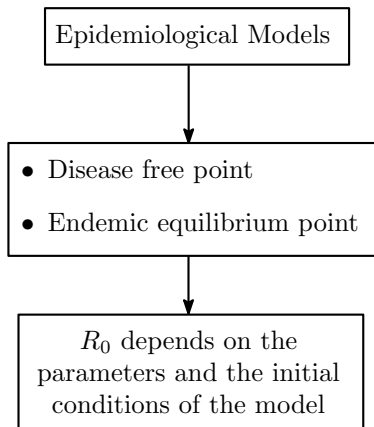
Epidemiological Models

```
graph TD; A[Epidemiological Models] --> B["• Disease free point<br/>• Endemic equilibrium point"]; B --> C["R0 depends on the<br/>parameters and the initial<br/>conditions of the model"];
```

- Disease free point
- Endemic equilibrium point

$R_0$  depends on the  
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# Can we apply this results to epidemiological models?



## SIR Model

$$\frac{dS}{dt} = -\beta SI$$

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$$\frac{dR}{dt} = \gamma I$$



## Can we apply this results to epidemiological models?

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